

ReScale4DL: Balancing Pixel and Contextual Information for Enhanced Bioimage Segmentation

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Deep learning has established itself as the state-of-the-art approach for segmentation in bioimage analysis. However, these powerful algorithms present an intriguing paradox regarding image resolution: contrary to intuition, lower-resolution images can yield superior performance for specific image analysis carried out by deep learning. This phenomenon is particularly significant in microscopy imaging, where high-resolution acquisitions come with substantial costs in throughput, data storage requirements, and potential photodamage to specimens. Through systematic experimentation, we evaluate how varying image resolution impacts deep learning performance in cellular image segmentation tasks. We trained popular architectures on datasets downsampled to 6-50% of their original resolution, mimicking acquisitions at lower image magnification, and compared their performance against models trained on native-resolution images. Our results show that segmentation accuracy either improves (by up to 25% of mean Intersection over Union (IoU)) or experiences only minimal degradation (< 5% of mean IoU) when using images downsampled by up to a factor of 4 (25% of the original resolution). This downsampling proportionally increases information throughput while reducing data storage requirements and inference time. With these findings, we contribute systematic guidelines to deep learning practitioners in creating efficient experimental pipelines for image-driven discoveries. This approach improves the sustainability and cost-effectiveness of bioimaging studies by reducing data and computing needs while optimising microscopy techniques.

deep learning | microscopy | image segmentation | receptive field | throughput | image resolution

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Introduction

Modern microscopy technologies have driven an unprecedented expansion in data volume. High-resolution techniques, particularly super-resolution microscopy (1), generate substantially larger datasets than traditional methods when imaging equivalent sample areas. A single 3D multichannel cell image from a spinning disk confocal requires approximately 1GB of storage (considering a size of 4MB for each slice of a three-channel and 100 *z*-slices volume). In contrast, the same field acquired with a super-resolution laser scanning microscope would be approximately 60 times larger (estimated from images acquired in-house). To ad-

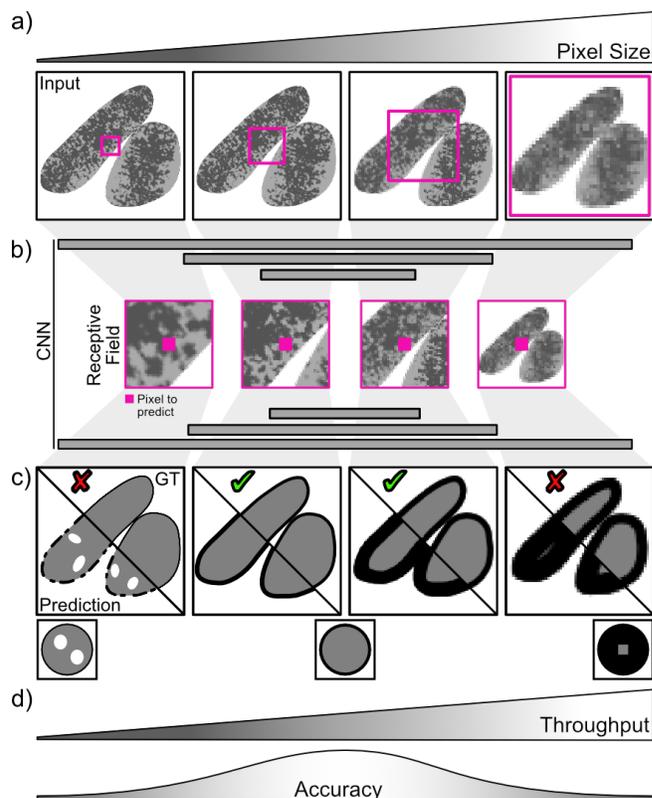


Fig. 1. The Image Resolution Paradox. The counterintuitive relationship between image resolution and deep learning performance emerges from the mismatch between pixel size and the network's receptive field. a) Decreasing image resolution (increasing pixel size) causes pixelation and limits observable details, yet may improve contextual information. b) The area observable within a convolutional neural network's (CNN) receptive field (magenta squares) determines the context available for predicting the value of a single pixel. c) Suboptimal pixel sizes lead to impaired predictions—either fragmented segmentations caused by non-continuous edges and inner pixels misclassified as background, referred to as false negatives (too high resolution) or over-generalisation at edges (too low resolution). d) Optimal image resolution for CNN-based processing depends on object size rather than maximal achievable microscopy resolution, and proper calibration can simultaneously enhance segmentation accuracy and experimental throughput.

dress the challenges in acquisition, storage, and processing posed by these volumes of data, researchers increasingly rely on deep learning approaches that automate analytical tasks while delivering reliable and reproducible results. For this, the bioimage analysis community has developed numerous

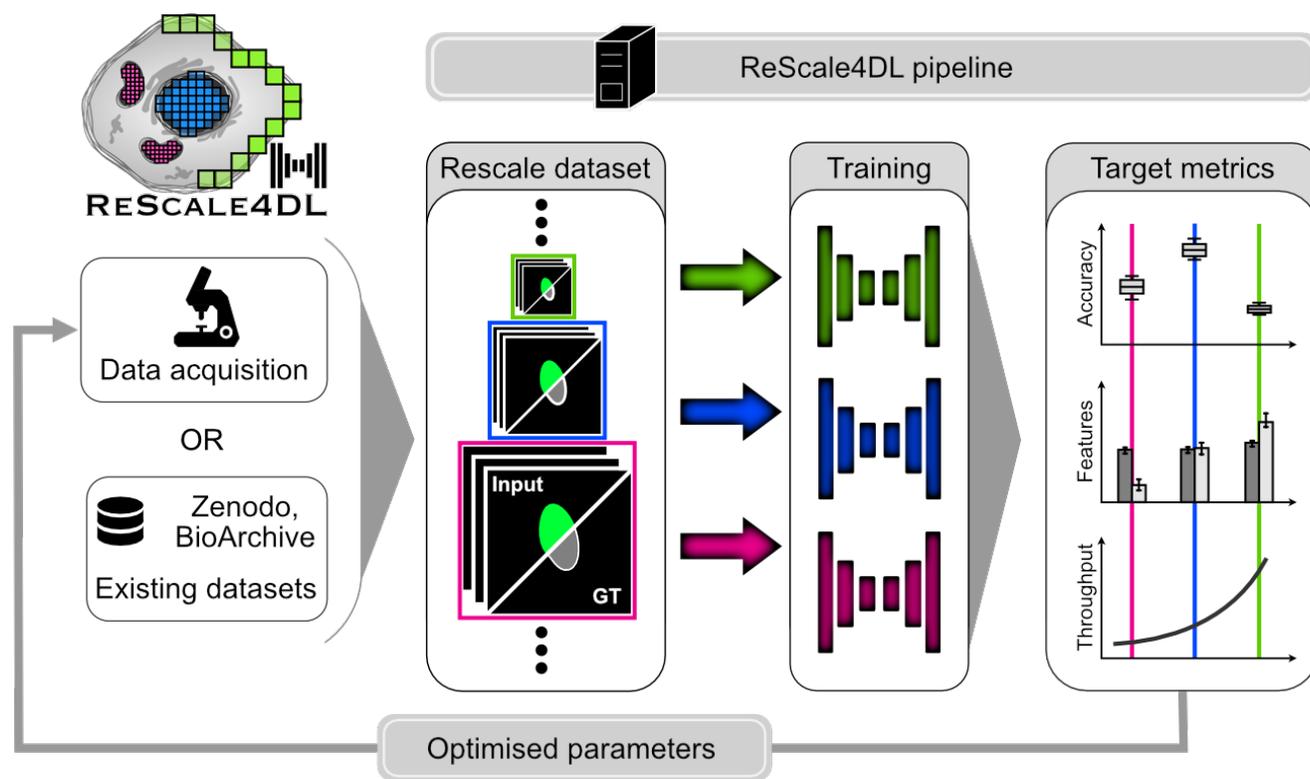


Fig. 2. ReScale4DL pipeline. Researchers can optimise the pixel size for a chosen deep learning architecture using their newly acquired and annotated images or on existing datasets, which can be used as a starting point for the optimisation. A series of image rescaling factors is applied to the data, a deep learning model is trained for each rescaled dataset, and different accuracy metrics and features are computed. Once an ideal target metric is chosen, such as the accuracy of the image processing performance, the recovery of an image feature, or a good compromise between the throughput and accuracy, researchers can identify an adequate pixel size and launch their imaging experiments with optimised image resolution. The results presented in this manuscript were obtained by following the ReScale4DL pipeline.

user-friendly solutions (2, 3), including standalone software and platform-integrated plugins (4–11), enabling researchers to leverage these powerful methodologies.

Yet, bioimage analysis faces unique efficiency challenges compared to other deep learning domains. The most significant bottlenecks include: limited computational resources and storage capacity, particularly problematic for time-lapse volumetric data; scarcity of large annotated datasets essential to train robust models and transfer learning (12, 13); and insufficient understanding of the relationship between image quality metrics and computational performance requirements (14, 15).

In computer vision, image quality often equates to an algorithm's efficiency in extracting relevant information under hardware constraints. Counterintuitively, a low-resolution image containing sufficient detail to perform the computational task accurately may be optimal, as it maximises the information-to-resource ratio. For instance, cell nuclei appear more homogeneous at lower resolutions, enabling neural networks to generalise more effectively. Conversely, at high resolution, nuclei images can display heterogeneous structures, introducing noise during segmentation and potentially increasing false negatives. This computational perspective contrasts with traditional microscopy practices, where image quality has been equated with higher resolution and magnification, assuming finer details provide more informative content (1). However, while visually appealing, the wealth of information in high-resolution images can be irrelevant

or even detrimental to computational analysis, as our results here demonstrate.

We present this phenomenon as the **image resolution paradox**: While high-resolution microscopy captures more detail, this additional data may contribute minimally—or even negatively—to a certain analysis task while requiring substantially greater resources. This paradox is particularly evident in deep learning-based pipelines (Fig. 1). The limitation stems from convolutional neural network's (CNN) receptive fields—the spatial region influencing a single output pixel. When image resolution exceeds the network's architectural optimum, pixels lack sufficient contextual information, compromising the model's performance. Although practitioners often address this by downsampling during pre-processing, incorporating resolution considerations directly into the experimental design would enable acquisition at optimal resolutions from the outset, simultaneously increasing throughput and reducing computational demands.

While this paradox is familiar to computer vision experts, few tools explicitly account for it. Cellpose (16) represents an exception, implementing automated re-sampling to optimise pixel-to-cell-diameter ratios. However, most users remain unaware of this critical consideration, leading to sub-optimal application of deep learning methods—particularly with architectures like vanilla U-Net—and unnecessary prioritisation of high-resolution acquisition despite its potential drawbacks.

In this study, we quantitatively demonstrate this paradox and

its impact on segmentation performance in bioimage analysis. For clarity, we define image resolution as the information content per pixel, separate from optical resolution considerations. We systematically evaluate resolution effects on model accuracy using a canonical 2D U-Net (17) for semantic segmentation and StarDist (9) for instance segmentation. Our experiments employ diverse specimens, including high-magnification *Caenorhabditis elegans* (*C. elegans*) (18) and brightfield *Escherichia coli* (*E. coli*) (19) images. Additionally, we analyse *Staphylococcus aureus* (*S. aureus*) imaged with Structural Illumination Microscopy (SIM), demonstrating that critical phenotypic changes remain detectable even when reducing resolution by 16 \times , enabling proportional throughput improvements. Beyond these examples, we provide a generalisable framework, ReScale4DL (<https://github.com/HenriquesLab/ReScale4DL>), that researchers can implement to determine optimal pixel sizes for their specific contexts, maximising both computational efficiency and information extraction (Fig. 2).

Results

High resolution and segmentation accuracy: a counter-intuitive relationship. We trained a 2D U-Net architecture to semantically segment different cellular regions - inner area, edges, and background - using two distinct datasets: *C. elegans* captured with brightfield microscopy and *E. coli* imaged via phase contrast microscopy. For each dataset, we systematically rescaled the images to multiple resolutions and trained separate U-Net models to evaluate performance across these conditions (Fig. 2). Since segmentation accuracy depends on the relationship between image resolution and object size, we quantified the performance relative to the percentage of an object's diameter covered by a single pixel. Our experiments revealed a counterintuitive relationship between resolution and segmentation quality (Fig. 3). Contrary to conventional expectations, high-resolution images often produced fragmented segmentation masks with unexpected discontinuities. In the *C. elegans* dataset, the inner masks produced at the original resolution contained spurious holes where pixels were misclassified as background (Fig. 3a)). This occurred because the model lacked sufficient contextual information to confidently identify inner and outer objects' areas and one-pixel width edges were under-represented for the given receptive field and resolution. Namely, the Intersection over Union (IoU) of semantic segmentations decreased by approximately 40% compared to binary segmentation, which remained relatively high (> 0.9) despite these deficiencies (Fig 3b)). Notably, downsampling the images improved accuracy metrics for both binary and semantic segmentation approaches, providing clear evidence that maximum resolution does not necessarily yield optimal segmentation results. The *E. coli* dataset analysis corroborated these findings (Fig. 3c-e)).

To ensure consistent comparison, we maintained identical U-Net architecture and hyperparameters across all experiments in Fig. 3, enabling direct assessment of resolution's impact

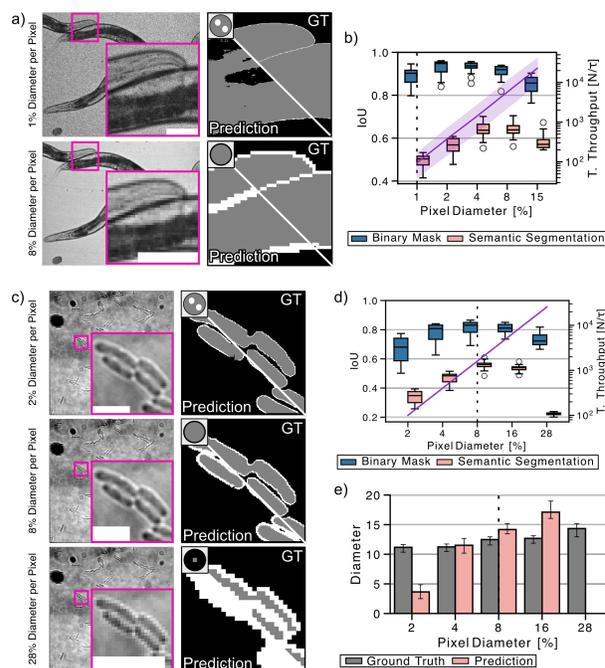


Fig. 3. Impact of image resolution on deep learning segmentation accuracy. A 2D U-Net architecture was employed for semantic segmentation of cellular regions (inner area and boundary) in microscopy images. Images were systematically resized to simulate varying acquisition resolutions, with a separate U-Net model trained for each resolution factor. a) Segmentation results for *Caenorhabditis elegans* (*C. elegans*) using original images (pixel covering $\sim 1\%$ of worm diameter) and images downsampled by factor 2^3 (pixel covering $\sim 8\%$ of worm diameter). Scale bars: 100 and 25 pixels, respectively. b) (Boxplots) Intersection over Union (IoU) distributions across downsampling factors ranging from $\times 1$ to $\times 2^4$, showing how segmentation accuracy varies with pixel size relative to object diameter. IoU was calculated both for semantic segmentation (average IoU of edge and inner regions) and binary masks (merged labels). (Purple line in logarithmic scale) Theoretical throughput was calculated as the number of objects observable by a unit of time (τ) given a certain resolution. τ is specific to each microscopy acquisition modality and preserved across the different resolutions. c-e) Equivalent analysis for *Escherichia coli* (*E. coli*) segmentation in phase contrast microscopy. c) Examples showing fragmented results (2% diameter coverage), optimal segmentation (8% coverage), and edge over-segmentation. Scale bars: 100, 25, and 10 pixels, respectively. d) IoU distribution (boxplots) and theoretical throughput (purple line in logarithmic scale) across varying bacteria diameter coverage ratios. e) Comparison between diameter distributions estimated from U-Net segmentation versus ground truth, with closest correspondence at 4% diameter coverage. Vertical dashed lines in panels b), d), and e) indicate the original dataset resolution.

on model performance. Both datasets' accuracy curves exhibited similar quadratic relationships between image resolution, object size, and IoU scores. For *C. elegans*, binary and semantic segmentation achieved peak IoU when pixels covered 2-4% and 4-8% of worm diameter respectively, demonstrating that optimal resolution differed from the original microscopy acquisition (1% coverage). Similarly, the *E. coli* dataset exhibited the highest IoU at comparable proportional resolutions: 4-16% diameter coverage per pixel for binary segmentation and 8-16% for semantic segmentation. This consistency across different biological specimens reveals a fundamental principle: our U-Net's 50×50 pixel receptive field imposes practical constraints. Objects with diameters exceeding 25 pixels (corresponding to $< 4\%$ diameter coverage per pixel) become problematic as their size exceeds the receptive field, while objects smaller than 6 pixels ($> 16\%$ diameter coverage) risk information dilution and loss through the network's operations. As exemplified, for any given CNN

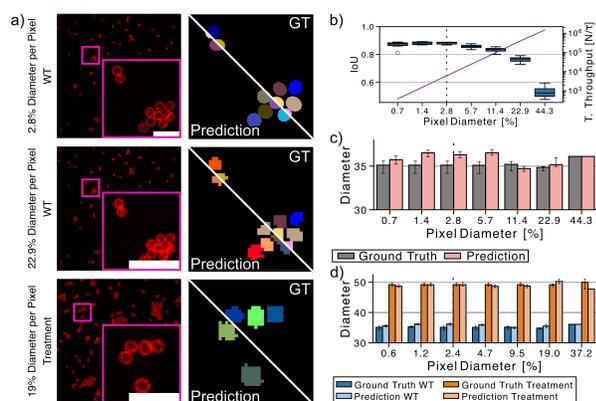


Fig. 4. Deep learning-driven resolution adjustment enables phenotype distinction while increasing imaging throughput. *Staphylococcus aureus* (*S. aureus*) bacteria were treated with FtsZ inhibitor PC190723, which prevents cell division and results in larger bacteria phenotypes (20). *S. aureus* (wild type (WT) and treated) were then imaged using Structured Illumination Microscopy (SIM) and segmented with StarDist. a) Representative images of *S. aureus* with ground truth (GT) segmentation and StarDist results at the original resolution (WT) and after 2^3 -factor downsampling (both WT and treated conditions). Scale bars: 100, 25, and 25 pixels, respectively. b) (Boxplots) Distribution of Intersection over Union (IoU) values of StarDist models trained and tested only with WT bacteria images across multiple resolution factors (upsampling: 2^{-2} to 2^0 ; downsampling: 2^1 to 2^4), showing the relationship between segmentation accuracy and the percentage of bacterial diameter covered by a single pixel. (Purple line in logarithmic scale) Theoretical throughput was calculated as the number of objects observable by a unit of time (τ) given a certain resolution. τ is specific to each microscopy acquisition modality and preserved across the different resolutions. c) Diameter distributions across resolution scales estimated from GT and the StarDist results for WT bacteria images in b). d) Comparison of the diameter distributions across various resolution scales for WT and treated bacteria. StarDist was trained with a mixed dataset containing WT and PC190723-treated *S. aureus* images in this case.

architecture, there exists an optimal resolution that maximises segmentation accuracy—and importantly, this resolution is typically significantly lower than what human observers prefer, allowing imaging pipelines with substantially improved throughput.

Optimising image resolution preserves phenotypic discrimination while maximising experimental throughput. Building upon our findings, we demonstrate how optimising image resolution preserves segmentation performance while enhancing experimental throughput. We tested this approach using *Staphylococcus aureus* (*S. aureus*) bacteria treated with antibiotic PC190723 and imaged via SIM. PC190723, a FtsZ inhibitor, prevents cell division and produces enlarged bacteria (20). To quantitatively assess this morphological effect, we employed StarDist—a deep learning approach optimised for instance segmentation of star-convex objects like round bacteria—to segment individual cells and measure diameter distributions (Fig. 4a)). As in our previous experiments, IoU values across different resolution factors revealed an optimal range where segmentation accuracy peaks. Notably, even at substantially reduced resolutions, StarDist maintained robust performance: with up to 11% of bacterial diameter covered by a single pixel, IoU values exceeded 0.8, and even with 23% coverage, IoU remained above 0.75 (Fig. 4b)). Analysis of wild-type (WT) diameter distributions confirmed that measurements derived from ground truth and StarDist predictions remained

consistent across resolutions ranging from 0.75% to 6% of diameter per pixel. Only at coverage ratios exceeding 11% (downsampling factor $> 2^3$) did diameter estimates begin to diverge, likely because objects were reduced to just a few pixels in width (Fig. 4c)). Most importantly, when training a StarDist model with WT and antibiotic-treated mixed bacteria populations, the diameter differences remained distinguishable across all sampling ratios, demonstrating that phenotypic discrimination is preserved even at significantly lower resolutions than typically employed (Fig. 4d)). Thus, by strategically reducing acquisition resolution, researchers can substantially increase imaging throughput and decrease acquisition times (Figs. 3b), 3d) and 4b)), enabling more comprehensive dataset collection for statistically robust experimental analyses.

Discussion

Our systematic investigation of the resolution paradox in deep learning-driven bioimage analysis reveals a fundamental trade-off between spatial resolution and computational performance. Our results demonstrate that popular methods like U-Net and StarDist (which often use a U-Net architecture) achieve optimal accuracy when image resolution is calibrated to match the network's receptive field with biological object dimensions, rather than maximising resolution. This finding challenges conventional microscopy practices while offering significant practical benefits for experimental workflows.

The paradox emerges from fundamental neural network characteristics. When object features exceed the receptive field (high resolution), networks lack sufficient context for consistent boundary prediction, resulting in fragmented masks with spurious discontinuities. Conversely, excessively downsampled images (low resolution) compress critical morphological features beyond recognition. Our quantitative analysis reveals a predictable quadratic relationship between object diameter coverage per pixel and segmentation accuracy, with optimal performance for the 2D U-Net consistently occurring when pixels cover 4-16% of object diameter—irrespective of the type of specimen or imaging modality. This optimal range represents a "sweet spot" where networks balance local detail with global context.

Most significantly, we demonstrated that models trained on optimally downsampled images maintain phenotypic discrimination capabilities. In the *S. aureus* antibiotic response experiment, critical morphological differences remained detectable even at $16\times$ lower resolution than commonly used (Fig. 4). This finding has profound implications for experimental design: researchers can substantially increase imaging throughput, reduce photobleaching and phototoxicity, minimise data storage requirements, and accelerate analysis pipelines—all without compromising biological insights (21, 22).

Although these principles are established in computer vision communities, they remain underappreciated in life sciences, where imaging protocols continue to emphasise the maximum achievable resolution regardless of computational anal-

ysis requirements. Our work provides a practical framework for biologists to determine optimal resolution parameters for their specific experimental contexts. By conducting preliminary resolution calibration studies before full-scale data acquisition, researchers can design more efficient imaging protocols that balance biological information content with computational performance.

The paradox persists in emerging transformer-based architectures despite their theoretical multi-scale capabilities. As demonstrated through MicroSAM (23) foundation model evaluations, fixed context windows in pre-trained models remain susceptible to resolution mismatches (Note 2, Fig. 5). However, the growing ecosystem of interactive tools like BioImage Model Zoo (6), MicroSAM (23) and DinoSim (24) creates opportunities for rapid empirical optimisation, turning this challenge into an accessible experimental design parameter.

Democratising AI in bioimaging requires deeper integration of data physics with model architectures. Current trends favour pre-trained "smart" solutions over adaptable systems, risking suboptimal application to novel experimental contexts. Future developments should prioritise dynamic acquisition systems that adjust resolution in real-time based on ongoing analysis, coupled with neural architectures explicitly encoding multi-scale relationships. By embedding these considerations into standard workflows, the field can achieve reproducible, resource-efficient microscopy pipelines that balance information content with computational sustainability.

Methods

Biological image datasets. Publicly available high-resolution *Caenorhabditis elegans* (*C. elegans*) minimum projection brightfield microscopy images and instance segmentation masks were obtained from (18). Publicly available *Escherichia coli* (*E. coli*) brightfield microscopy images and instance segmentation masks dataset was obtained from (19), which is available on Zenodo 10.5281/zenodo.5550934. In-house acquired super-resolution *Staphylococcus aureus* (*S. aureus*) cell wall structured illumination microscopy (SIM) fluorescence images and annotated instance segmentation masks dataset available on Zenodo 10.5281/zenodo.15169017.

Dataset re-sampling. ReScale4DL Python library (<https://github.com/HenriquesLab/ReScale4DL>) was used to resize raw images and their respective masks. For *C. elegans* and *E. coli*, the instance masks were first rescaled and then, the edges and inner side were estimated using the ImageJ macro available in DeepBacs GitHub repository (19) (<https://github.com/HenriquesLab/DeepBacs/>). Upsampling was computed with `catmull-rom` interpolation and nearest-neighbor interpolation methods for the raw and the mask images, respectively (all available within the NanoPyx Python package (25)). Downsampling was computed with binning and `transform.rescale` from `scikit-image` for the raw images and the masks respec-

tively. *C. elegans* dataset was downsampled by factors 2, 2², 2³, and 2⁴. *E. coli* was upsampled by factors 2 and 2² and downsampled by factors 2 and 2². *S. aureus* was upsampled by factors 2 and 2² and downsampled by factors 2, 2², 2³, and 2⁴.

Segmentation networks. The 2D Multilabel U-Net and 2D StarDist (9) ZeroCostDL4Mic (2) notebooks were used with DL4MicEverywhere (11) with the hyperparameter configuration in Table 1.

Evaluation. The Intersection over Union (IoU) scores visualised in Figs 3 and 4 were computed for the results of all the models specified in Table 1, and for the binary segmentation (*C. elegans* and *E. coli*), semantic segmentation (*C. elegans* and *E. coli*) and instance segmentation (*S. aureus*) results. For each object j in an image i , the diameter D_{ij} of non-rounded shapes (*C. elegans* and *E. coli* datasets) was computed as the median of the Euclidean Distance Transform (EDT) values contained in the object's skeleton. For *S. aureus* dataset, D_{ij} of each bacteria was estimated by solving the equation of the circle area, given as

$$D_{ij} = 2 \cdot \sqrt{\frac{A_{ij}}{\pi}} \quad (1)$$

where A_{ij} is the area of the object j in the image i , measured as the sum of all the pixels in the object. To compute the average portion of diameter covered by one pixel, we first computed the average diameter for each scaling factor, D_s as

$$D_s = \frac{1}{N} \sum_{i=1}^N \left(\frac{1}{O_i} \sum_{j=1}^{O_i} D_{ij} \right), \quad s \in [2^{\mathbf{Z}[-2,4]}] \quad (2)$$

where O_i is the total number of objects in the image i , N is the total number of images in the dataset and s is the rescaling factor. Then, D_s was inverted and multiplied by 100 to compute the portion of diameter covered by one pixel.

To measure the throughput achievable for each rescaling factor s , we first estimated the average area in pixels of each object in an image in pixels (A_s). Then, we consider the size of the achievable field of view (FOV) for a camera as the area in pixels of the images in the original dataset (CAM_{FOV}). Considering the throughput as the amount of information recordable per unit of time, we computed the throughput as

$$TH_s = \frac{CAM_{FOV}}{A_s} \times \frac{1}{\tau}, \quad s \in [2^{\mathbf{Z}[-2,4]}] \quad (3)$$

where τ is the time required to acquire a FOV. In other words, TH_s provides an estimate of the number of objects that can be captured by a unit of time, yet, using Equation 3 with preliminary information about the sample's morphology and microscopy camera features, it is possible to compute this value easily.

Code availability. The code for rescaling the images and computing the metrics is available at <https://github.com/HenriquesLab/ReScale4DL>. The

notebooks to train, test and deploy inference are available through the DL4MicEverywhere (<https://github.com/HenriquesLab/DL4MicEverywhere>) platform.

Data availability. WT and antibiotic-treated super-resolution *Staphylococcus aureus* (*S. aureus*) cell wall SIM images together with instance segmentation annotations are available on Zenodo <https://zenodo.org/records/15169018>.

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Supplementary Note 1: Deep learning model training hyperparameters

<i>C. elegans</i>		<i>E. coli</i>		<i>S. aureus</i>	
Network	2D U-Net	Network	2D U-Net	Network	2D StarDist
Epochs	1000	Epochs	1000	Epochs	1000
Patch size (per resizing factor)	512 ($\times 2^{-2, -1, 0}$) 256 ($\times 2$) 128 ($\times 2^2$) 64 ($\times 2^3$) 32 ($\times 2^4$)	Patch size (per resizing factor)	512 ($\times 2^{-2, -1, 0}$) 256 ($\times 2$) 128 ($\times 2^2$)	Patch size (per resizing factor)	2048 ($\times 2^{-2, -1, 0}$) 1184 ($\times 2$) 576 ($\times 2^2$) 272 ($\times 2^3$) 128 ($\times 2^4$)
Batch size	5	Batch size	5	Batch size	2
Validation [%]	10	Validation [%]	10	Validation [%]	10
Learning rate	0.0001	Learning rate	0.0001	Learning rate	0.0003
Pooling steps	2	Pooling steps	2	Grid parameter	2
Minimal fraction	0.05	Minimal fraction	0.05	Number of rays	32

Table 1. The network architecture and the training parameters for each dataset were preserved. The patch size for the input during training was dynamically changed with the image resizing to maintain the same field of view, except for the upsampling due to limited GPU capabilities. The values $2^{-2, -1}$ correspond to image upsamplings, 2^0 is the original image resolution and $2^{1, \dots, 4}$ correspond to image downsampling.

Supplementary Note 2: Optimising the pixel size for foundation models

Here we provide a visual example of segmentation performance using foundation models for images with different pixel sizes. We performed instance segmentation of *Escherichia coli* (*E. coli*), *Caenorhabditis elegans* (*C. elegans*), and *Staphylococcus aureus* (*S. aureus*) samples using MicroSAM (23) software, with the same rescaling factors used for the Figs. 2 and 4. For simplicity, we used their 2D Annotator plugin in Napari to deploy interactive segmentation with a single-point prompt-based approach, followed by the automatic instance segmentation. Rescaled images were individually segmented by manually pointing to the same structural landmark each time. For all experiments, we chose the Vision Transformer (ViT) Large backbone architecture, a fine-tuned version of the original Segment Anything Model (SAM) (26) for cellular and nuclear segmentation in light microscopy (ViT-1-1m). Importantly, the segmentation results provided here may not be optimal and only aim to show the variability of the model according to the image resolution under the same conditions. Indeed, the results could be improved by changing the prompt or by increasing their number.

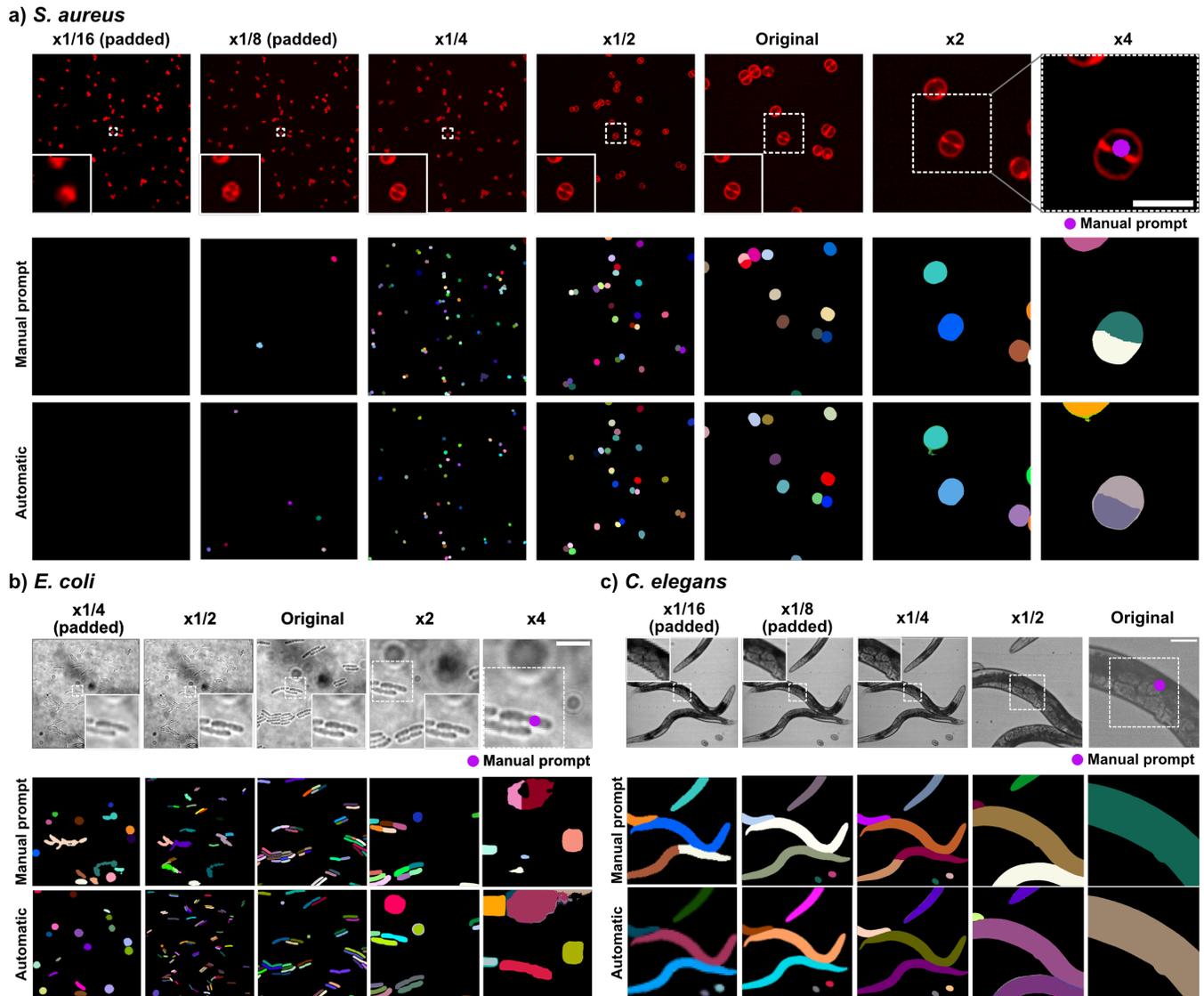


Fig. 5. Segmentation results of Segment Anything for Microscopy on images with different pixel sizes using a single point prompting. MicroSAM (23) was used to obtain the instance segmentation of a) *S. aureus*, b) *E. coli* and c) *C. elegans* example images. For simplicity, we followed a single point-wise prompting strategy, pointing to the same object on each rescaled image (*i.e.*, the manual prompt was the same on each panel), and run the automatic instance segmentation pipeline. All the images matched model input dimensions (512×512 pixels) to avoid internal tiling or image re-scaling. The images that had smaller dimensions were padded with zeros. Scale bars correspond to $25 \mu\text{m}$ for a), and $50 \mu\text{m}$ for b-c). Square boxes correspond to the same physical area on each image.